

The Skinner-Rusk formalism in higher field theories

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- 1 Multisymplectic Geometry
- 2 Jet Bundles
- 3 The Skinner-Rusk Formalism



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Symplectic Geometry

Definition

$\Omega \in \Lambda^2 M$ is **symplectic** iff

- nondegenerate: $i_v \Omega = 0 \Leftrightarrow v = 0$,
 - closed: $d\Omega = 0$.
-
- $m = \dim M = 2n$
 - (M, Ω) is called a symplectic manifold.
 - $\Omega^n / n!$ is the symplectic volume (or the Liouville measure).
 - Musical isomorphisms: $TM \begin{matrix} \xrightarrow{\flat} \\ \xleftarrow{\sharp} \end{matrix} T^*M$.

Theorem (Darboux)

$$\Omega = \sum_{i=1}^n dq^i \wedge dp_i$$

Cosymplectic Geometry

Definition

(M^{2n+1}, Ω, μ) is **cosymplectic** iff

- nondegenerate: $\Omega^n \wedge \mu \neq 0$,
- closed: $d\Omega = 0$ and $d\mu = 0$.

The musical isomorphism $b : \mathfrak{X}M \rightarrow \Lambda M$ is given by

$$b(v) := i_v \Omega + \mu(v)\mu.$$

The Reeb vector field $R := b^{-1}(\mu)$ is given by the equations:

$$i_R \Omega = 0 \quad \text{and} \quad i_R \mu = 1.$$

Theorem (Darboux)

$$\Omega = \sum_{i=1}^n dq^i \wedge dp_i \quad \text{and} \quad dt = \mu$$

Example (T^*Q as a symplectic manifold)

Let $M = T^*Q$ and $\Omega = -d\Theta$, where Θ is the Liouville one-form

$$\Theta = p_i dq^i.$$

Then (T^*Q, Ω) is a symplectic manifold and

$$\Omega = dq^i \wedge dp_i.$$

Example ($\mathbb{R} \times T^*Q$ as a cosymplectic manifold)

Let $M = \mathbb{R} \times T^*Q$, $\Omega = dq^i \wedge dp_i$ and $\mu = dt$. Then $(\mathbb{R} \times T^*Q, \Omega, \mu)$ is a cosymplectic manifold.



Mechanics (the symplectic case)

- 1 The Lagrangian $L : TQ \longrightarrow \mathbb{R}$.
- 2 The Legendre transform $FL : TQ \longrightarrow T^*Q$,
 $FL(q^i, \dot{q}^i) = (q^i, \hat{p}_i = \frac{\partial L}{\partial \dot{q}^i})$.
- 3 The Poincaré-Cartan 1-form $\Theta_L := FL^*\Theta = \frac{\partial L}{\partial \dot{q}^i} dq^i$.
- 4 The Poincaré-Cartan 2-form $\Omega_L := -d\Theta_L = dq^i \wedge d\hat{p}_i$.
- 5 (TQ, Ω_L) is symplectic whenever L is regular.
- 6 The Lagrangian energy $E_L(= \hat{p}) := \dot{q}^i \hat{p}_i - L = \dot{q}^i \frac{\partial L}{\partial \dot{q}^i} - L$.
- 7 A Lagrangian vector field $X \in \mathfrak{X}(TQ)$ satisfies $i_X \Omega_L = dE$.

Theorem

Let $X \in \mathfrak{X}(TQ)$ be a second-order vector field. The integral curves of X satisfy the Euler-Lagrange equations:

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}^i} \right) - \frac{\partial L}{\partial q^i} = 0.$$

Mechanics (the cosymplectic case)

- 1 The Lagrangian $L : \mathbb{R} \times TQ \longrightarrow \mathbb{R}$.
- 2 The Legendre transform $FL : \mathbb{R} \times TQ \longrightarrow \mathbb{R} \times T^*Q$,
 $FL(t, q^i, \dot{q}^i) = (t, q^i, \hat{p}_i = \frac{\partial L}{\partial \dot{q}^i})$.
- 3 The Hamiltonian energy $H = (FL^{-1})^* E_L = \dot{q}^i p_i - L \circ FL^{-1}$.
- 4 The forms $\Theta_H := \Theta - H dt$ and $\Omega_H := \Omega + dH \wedge dt$.
- 5 The Poincaré-Cartan 1-form $\Theta_L := FL^* \Theta_H = \frac{\partial L}{\partial \dot{q}^i} dq^i - E_L dt$.
- 6 The Poincaré-Cartan 2-form $\Omega_L := -d\Theta_L = dq^i \wedge d\hat{p}_i - dt \wedge d\hat{p}$.
- 7 $(\mathbb{R} \times TQ, \Omega_L, dt)$ is cosymplectic whenever L is regular.

Theorem

The integral curves of the Reeb vector field satisfy the Euler-Lagrange equations:

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}^i} \right) - \frac{\partial L}{\partial q^i} = 0.$$

Definition

$\Omega \in \Lambda^k M$ is **multisymplectic** iff

- nondegenerate: $i_v \Omega = 0 \Leftrightarrow v = 0$,
- closed: $d\Omega = 0$.

- (M, Ω) is called a multisymplectic manifold.
- Musical morphisms: $\hat{\Omega}_j : \mathfrak{X}^j \longrightarrow \Lambda^{k-j}$.



Multisymplectic examples

Example ($\Lambda^k Q$ as a multisymplectic manifold)

Let $M = \Lambda^k Q$ and $\Omega = -d\Theta$, where Θ is the Liouville k -form

$$\Theta_\alpha(X_1, \dots, X_k) := \alpha(\nu_* X_1, \dots, \nu_* X_k).$$

In coordinates,

$$\Theta = p_{i_1, \dots, i_k} dq^{i_1} \wedge \dots \wedge dq^{i_k}.$$

Then $(\Lambda^k Q, \Omega)$ is a multisymplectic manifold and

$$\Omega = -dp_{i_1, \dots, i_k} \wedge dq^{i_1} \wedge \dots \wedge dq^{i_k}.$$

Example ($\Lambda_r^k Q$ as a multisymplectic manifold)

$\Lambda_r^k Q$ is the set of the r -horizontal k -forms (with respect to a fibration $\pi : Q \rightarrow P$). Let Ω_r be the restriction of Ω . Then $(\Lambda_r^k Q, \Omega_r)$ is a multisymplectic manifold.

The Multi-Index Notation

Usually, given a function $f : \mathbb{R}^m \rightarrow \mathbb{R}$, its partial derivatives are denoted by

$$f_{i_1 i_2 \dots i_k} = \frac{\partial^k f}{\partial x^{(i_1, i_2, \dots, i_k)}} := \frac{\partial^r f}{\partial x_{i_1} \partial x_{i_2} \dots \partial x_{i_k}}.$$

What matters is not the order in which the derivatives are taken, but the number of times with respect to each variable.

Definition

- A **multi-index** is a m -tuple $I \in \mathbb{N}^m$.
- The i -th component of I is denoted $I(i)$.
- Addition and “subtraction” of multi-indexes are defined componentwise, $(I \pm J)(i) = I(i) \pm J(i)$.
- The length of I is the sum $|I| = \sum_i I(i)$, and its factorial $I! = \prod_i I(i)!$.
- $\mathbf{1}_i = (\delta_j^i) = (0, \dots, 1, \dots, 0)$.

The Multi-Index Notation

We will denote the partial derivatives of a function $f : \mathbb{R}^m \longrightarrow \mathbb{R}$ by

$$f_I = \frac{\partial^{|I|} f}{\partial x^I} := \frac{\partial^{I(1)+I(2)+\dots+I(m)} f}{\partial x_1^{I(1)} \partial x_2^{I(2)} \dots \partial x_m^{I(m)}}.$$

Given $f : \mathbb{R}^3 \longrightarrow \mathbb{R}$,

- $\frac{\partial^3 f}{\partial x_1 \partial x_2 \partial x_1}$ will be $f_{(2,1,0)}$ instead of f_{121} .
- $\frac{\partial}{\partial x_1} \frac{\partial^2 f}{\partial x_2 \partial x_1}$ will be $f_{(1,1,0)+1_1}$ (or $f_{(2,0,0)+1_2}$).



The Multi-Index Notation

Lemma

- $\sum_{l+1_i=J} \frac{l(i) + 1}{|l| + 1} = 1$
- $\sum_{|l|=l-1} \sum_{i=0}^m a_{l,i} = \sum_{|j|=l} \sum_{l+1_i=j} a_{l,i}$
- $\sum_{|j|=l} b^j a_j = \sum_{|l|=l-1} \sum_{i=1}^m \frac{l(i) + 1}{|l| + 1} (b^{l+1_i} + Q^{l,i}) a_{l+1_i}$ where
 $\sum_{l+1_i=J} \frac{l(i) + 1}{|l| + 1} Q^{l,i} = 0$



Definition

- (E, π, M) will be a fiber bundle ($\dim M = m$ and $\dim E = m + n$).
- Adapted coordinated systems will be of the form (x^i, u^α) .
- $\phi, \psi \in \Gamma(E)$ are **k -equivalent** at p if for all α, i_j and r

$$\phi(p) = \psi(p) \text{ and } \left. \frac{\partial^r \phi^\alpha}{\partial x^{i_1} \dots \partial x^{i_r}} \right|_p = \left. \frac{\partial^r \psi^\alpha}{\partial x^{i_1} \dots \partial x^{i_r}} \right|_p.$$

Definition

- The k -jet of ϕ at p is $j_p^k \phi := [\phi]_p^k$.
- The k -th jet manifold of π is $J^k \pi := \{j_p^k \phi : p \in M, \phi \in \Gamma_p(\pi)\}$.

Adapted coordinates (x^i, u^α) on E induce adapted coordinates (x^i, u_i^α) on $J^k \pi$ (with $0 \leq |I| \leq k$):

$$u_i^\alpha(j_p^k \phi) = \left. \frac{\partial^{|I|} \phi^\alpha}{\partial x^I} \right|_p.$$



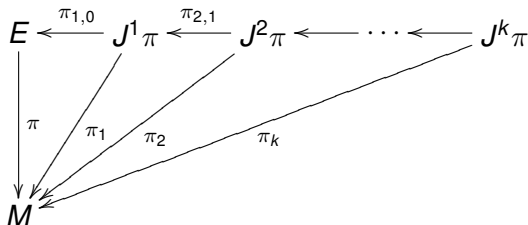
Properties

- $(J^k \pi, \pi_k, M)$ is a fiber bundle, where

$$\pi_k(j_p^k \phi) = p \quad (\text{in coordinates } \pi_k(x^i, u_j^\alpha) = (x^i)).$$

- $J^k \pi$ fibers over the l -jet manifolds $J^l \pi$ ($l \leq k$), where

$$\pi_{k,l}(j_p^k \phi) = j_p^l \phi \quad (\text{in coord. } \pi_{k,l}(x^i, u_j^\alpha) = (x^i, u_j^\alpha), |I| \leq k, |J| \leq l).$$



- $(J^k \pi, \pi_{k,k-1}, J^{k-1} \pi)$ is an affine fiber bundle.



The (extended) dual affine bundle

Definition

- The *extended dual affine bundle* $(J^k \pi^\dagger, \pi_{k,k-1}^\dagger, J^{k-1} \pi)$ is a fiber bundle whose fibers consist of affine maps of the corresponding fibers of the affine bundle $(J^k \pi, \pi_{k,k-1}, J^{k-1} \pi)$.
- The *dual affine bundle* $(J^k \pi^*, \pi_{k,k-1}^*, J^{k-1} \pi)$ is a fiber bundle whose fibers consist of classes of affine maps of the corresponding fibers of the affine bundle $(J^k \pi, \pi_{k,k-1}, J^{k-1} \pi)$, which differ by a constant.



The (extended) dual affine bundle

Definition

- The *extended dual affine bundle* $(J^k \pi^\dagger, \pi_{k,k-1}^\dagger, J^{k-1} \pi)$.
- The *dual affine bundle* $(J^k \pi^*, \pi_{k,k-1}^*, J^{k-1} \pi)$.
- There exist canonical isomorphisms $J^k \pi^\dagger \approx \Lambda_2^m(J^{k-1} \pi)$ and $J^k \pi^* \approx \Lambda_2^m(J^{k-1} \pi) / \Lambda_1^m(J^{k-1} \pi)$.
- If $\omega \in \Lambda_2^m(J^{k-1} \pi)$, then $\omega = p d^m x + p_\alpha^{l,i} du_l^\alpha \wedge d^{m-1} x_i$, $|l| \leq k-1$. Thus we have coordinates $(x^i, u_l^\alpha, p, p_\alpha^{l,i})$ on $\Lambda_2^m(J^{k-1} \pi)$.
- There is a **natural pairing** between $J^k \pi$ and $J^k \pi^\dagger$, $\Phi(j_x^k \phi, \omega_{j_x^{k-1} \phi}) := a(x)$, such that $a(x)\eta(x) = (j^{k-1} \phi)^* \omega_{j_x^{k-1} \phi}$. In coordinates: $\Phi(x^i, u_l^\alpha, u_K^\alpha, p_\alpha^{l,i}, p) = p_\alpha^{l,i} u_{l+1,i}^\alpha + p$.
- $\Lambda_2^m(J^{k-1} \pi)$ has a canonical multisymplectic structure,

$$\Omega = -dp \wedge d^m x - dp_\alpha^{l,i} \wedge du_l^\alpha \wedge d^{m-1} x_i.$$



Mechanics (the multisymplectic case)

- 1 The Lagrangian $L : J^1\pi \longrightarrow \mathbb{R}$.
- 2 Let $\hat{p}_\alpha^i = \frac{\partial L}{\partial u_i^\alpha}$ and $\hat{p} = L - u_i^\alpha \hat{p}_\alpha^i$.
- 3 The Poincaré-Cartan m -form $\Theta_L := \hat{p}_\alpha^i du^\alpha \wedge d^{m-1}x_i + \hat{p} d^m x$.
- 4 The Poincaré-Cartan $(m+1)$ -form $\Omega_L := -d\Theta_L$.
- 5 $(J^1\pi, \Omega_L)$ is multisymplectic whenever L is regular.

Theorem

A section $\phi : M \longrightarrow E$ satisfies the Euler-Lagrange equations

$$(j^1\phi)^* \left(\frac{\partial L}{\partial u^\alpha} - \frac{d}{dx^i} \frac{\partial L}{\partial u_i^\alpha} \right) = 0$$

iff $\forall X \in \mathfrak{X}(J^1\pi)$

$$(j^1\phi)^*(i_X\Omega_L) = 0.$$

Mechanics (the multisymplectic case)

The DeDonder equations

Definition

A section $\sigma : M \longrightarrow J^1\pi$ satisfies the *DeDonder equations* iff

$$(\sigma)^*(i_X\Omega_L) = 0, \quad \forall X \in \mathfrak{X}(J^1\pi).$$

Theorem

Let Γ be a connection in $\pi_1 : J^1\pi \longrightarrow M$ whose horizontal projector \mathbf{h} satisfies

$$i_{\mathbf{h}}\Omega_L = (m-1)\Omega_L.$$

The integral sections of Γ satisfies the DeDonder equations.



- 1 Consider the fibered product $W_0 := J^1\pi \times_E \Lambda_2^m E$.
- 2 The pairing $\Phi(x^i, u^\alpha, u_j^\alpha, p_\alpha^i, p) = p_\alpha^i u_j^\alpha + p$.
- 3 The dynamical function $H := \Phi - L \circ pr_1$.
- 4 The canonical multisymplectic $(m+1)$ -form $\Omega = -dp \wedge d^m x - dp_\alpha^i \wedge du^\alpha \wedge d^{m-1} x_i$.
- 5 The $(m+1)$ -form $\Omega_0 := \Omega + dH \wedge \mu$.
- 6 We search an Ehresmann connection in the fibered bundle $\pi_{W_0, M} : W_0 \rightarrow M$ whose horizontal projector is the solution of

$$i_{\mathbf{h}} \Omega_0 = (m-1) \Omega_0.$$



- 1 Consider the fibered product $W_0 := J^k \pi \times_{J^{k-1} \pi} \Lambda_2^m(J^{k-1} \pi)$.
- 2 The pairing $\Phi(x^i, u_j^\alpha, u_K^\alpha, p_\alpha^{l,i}, p) = p_\alpha^{l,i} u_{l+1}^\alpha + p$.
- 3 The dynamical function $H := \Phi - L \circ pr_1$.
- 4 The canonical multisymplectic $(m+1)$ -form
$$\Omega = -dp \wedge d^m x - dp_\alpha^{l,i} \wedge du_j^\alpha \wedge d^{m-1} x_i.$$
- 5 The $(m+1)$ -form $\Omega_0 := \Omega + dH \wedge \mu$.
- 6 We search an Ehresmann connection in the fibered bundle $\pi_{W_0, M} : W_0 \longrightarrow M$ whose horizontal projector is the solution of

$$i_h \Omega_0 = (m-1) \Omega_0.$$



Solving the Skinner-Rusk equation

We first have to restrict to the space where solutions exist:

$$W_1 := \{w \in W_0 / \exists \mathbf{h}_w : T_w W_0 \longrightarrow T_w W_0 \text{ linear s.t. } \mathbf{h}_w^2 = \mathbf{h}_w, \\ \ker \mathbf{h}_w = (V\pi_{W_0, M})_w, i_{\mathbf{h}_w} \Omega_{H_0}(w) = (m-1)\Omega_{H_0}(w)\}.$$

The projectors must have the form

$$\mathbf{h}_w = \left(\frac{\partial}{\partial x^i} + A_{Ji}^\alpha \frac{\partial}{\partial u_J^\alpha} + B_{\alpha i}^{lj} \frac{\partial}{\partial p_\alpha^{lj}} + C_j \frac{\partial}{\partial p} \right) \otimes dx^i.$$

We start to compute...



Solving the Skinner-Rusk equation

$$\begin{aligned}
 & i_{h_w} \Omega_0 - (m-1)\Omega_0 = \\
 & = \left(B_{\alpha i}^{l,i} du_l^\alpha - A_{li}^\alpha dp_\alpha^{l,i} + p_\alpha^{l,i} du_{l+1}^\alpha + u_{l+1}^\alpha dp_\alpha^{l,i} - \frac{\partial L}{\partial u_j^\alpha} du_j^\alpha \right) \wedge d^m x \\
 & = \left[\left(B_{\alpha i}^i - \frac{\partial L}{\partial u^\alpha} \right) du^\alpha + \sum_{|l|=1}^{k-1} \left(B_{\alpha i}^{l,i} - \frac{\partial L}{\partial u_l^\alpha} \right) du_l^\alpha + \sum_{j=0}^{k-2} p_\alpha^{l,i} du_{l+1}^\alpha \right. \\
 & \quad + \sum_{|K|=k} - \frac{\partial L}{\partial u_K^\alpha} du_K^\alpha + \sum_{K'=k-1} p_\alpha^{K',i} du_{K'+1}^\alpha \\
 & \quad \left. + \sum_{|l|=0}^{k-1} (u_{l+1}^\alpha - A_{li}^\alpha) dp_\alpha^{l,i} \right] \wedge d^m x
 \end{aligned}$$

Equating to zero...



Solving the Skinner-Rusk equation

$$B_{\alpha j}^j = \frac{\partial L}{\partial u^\alpha};$$

$$p_\alpha^{l,i} = \frac{l(i) + 1}{|l| + 1} \left(\frac{\partial L}{\partial u_{l+1,i}^\alpha} - B_{\alpha j}^{l+1,j} + Q_\alpha^{li} \right), \text{ with } |l| = 0, \dots, k - 2;$$

$$p_\alpha^{l,i} = \frac{l(i) + 1}{|l| + 1} \left(\frac{\partial L}{\partial u_{l+1,i}^\alpha} + Q_\alpha^{li} \right), \text{ with } |l| = k - 1;$$

$$A_{ji}^\alpha = u_{l+1,i}^\alpha, \text{ with } |l| = 0, \dots, k - 1;$$

Getting rid of the Q 's...



Solving the Skinner-Rusk equation

We finally obtain:

$$B_{\alpha j}^j = \frac{\partial L}{\partial u^\alpha}; \quad (1)$$

$$\sum_{l+1_j=J} p_\alpha^{l,i} = \frac{\partial L}{\partial u_J^\alpha} - B_{\alpha j}^j, \text{ with } |I| = 1, \dots, k-1; \quad (2)$$

$$\sum_{l+1_j=K} p_\alpha^{l,i} = \frac{\partial L}{\partial u_K^\alpha}, \text{ with } |K| = k; \quad (3)$$

$$A_{li}^\alpha = u_{l+1_j}^\alpha, \text{ with } |I| = 0, \dots, k-1.$$

Regularity, $\mathbf{h}_w(T_w W_0) \subset i_*(TW_2) \forall w \in W_2$,

$$\sum_{l+1_j=K} B_{\alpha j}^{li} = \frac{\partial^2 L}{\partial x^j \partial u_K^\alpha} + u_{l+1_j}^\beta \frac{\partial^2 L}{\partial u_l^\beta \partial u_K^\alpha} + A_{K'j}^{\alpha'} \frac{\partial^2 L}{\partial u_{K'}^{\alpha'} \partial u_K^\alpha}, \text{ with } |K| = k. \quad (4)$$

The first order case ($k=1$)

Main equations

$$B_{\alpha j}^j = \frac{\partial L}{\partial u^\alpha};$$
$$p_\alpha^j = \frac{\partial L}{\partial u_i^\alpha}.$$

Regularity condition

$$B_{\alpha j}^i = \frac{\partial^2 L}{\partial x^j \partial u_i^\alpha} + u_j^\beta \frac{\partial^2 L}{\partial u^\beta \partial u_i^\alpha} + A_{i'j}^{\alpha'} \frac{\partial^2 L}{\partial u_{i'}^{\alpha'} \partial u_i^\alpha}.$$



The one-dimensional case ($m = 1$)

Main equations

$$\begin{aligned} B_\alpha &= \frac{\partial L}{\partial u^\alpha}; \\ p_\alpha^j &= \frac{\partial L}{\partial u_j^\alpha} - B_\alpha^{j+1}, \text{ with } j = 1, \dots, k-1; \\ p_\alpha^k &= \frac{\partial L}{\partial u_k^\alpha}. \end{aligned}$$

Regularity condition

$$B_\alpha^k = \frac{\partial^2 L}{\partial x \partial u_k^\alpha} + u_{i+1}^\beta \frac{\partial^2 L}{\partial u_i^\beta \partial u_k^\alpha} + A_{k'}^{\alpha'} \frac{\partial^2 L}{\partial u_{k'}^{\alpha'} \partial u_k^\alpha}.$$



$$W_2 := \{w \in W_1 : H(w) = 0\} = \{w \in W_0 : (3) \text{ and } H(w) = 0\}$$

Theorem

(W_2, Ω_2) is multisymplectic iff L is regular ($\det \left(\frac{\partial^2 L}{\partial u_K^\alpha \partial u_{K'}^{\alpha'}} \right) \neq 0$).

What now?

- Higher-order Euler-Lagrange equations.
- Higher-order Gotay-Nester-Hinds algorithm.
- Higher-order control theory (María Barbero).
- Higher-order paella.



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- Higher-order paella.



Higher-order Euler-Lagrange equations

Given an Ehresmann connection on $\pi_{W_2M} : W_2 \rightarrow M$, whose horizontal projector \mathbf{h} is a solution of the Skinner-Rusk equation

$$i_{\mathbf{h}}\Omega_2 = (m - 1)\Omega_2,$$

consider the “horizontal projector” $\bar{\mathbf{h}} = i_*\mathbf{h}i_*^{-1}$ defined on $i_*(TW_2)$.

Theorem

Let σ be a section of $\pi_{W_2M} : W_2 \rightarrow M$ and denote $\bar{\sigma} = i \circ \sigma$. If σ is an integral section of \mathbf{h} , then σ is holonomic,

$$pr_1 \circ \bar{\sigma} = j^k(\pi_{W_2M} \circ \sigma),$$

and satisfies the higher-order Euler-Lagrange equations:

$$j^{2k}(\pi_{W_2M} \circ \sigma)^* \left(\sum_{|J|=0}^k (-1)^{|J|} \frac{d^{|J|}}{dx^J} \frac{\partial L}{\partial u_J^\alpha} \right) = 0.$$



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The End

- All that has a beginning has an end.
(The Oracle, *The Matrix Trilogy*)

